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**By Anna Nagurney**

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[http://www.academia.edu/3167003/A\\_retrospective\\_on\\_Beckmann\\_McGuire\\_and\\_Winstens\\_Studies\\_in\\_the\\_Economics\\_of\\_Transportation](http://www.academia.edu/3167003/A_retrospective_on_Beckmann_McGuire_and_Winstens_Studies_in_the_Economics_of_Transportation)

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In other words, we say that  $x$  is a stationary point or an equilibrium point if, once the projected dynamical system is at  $x$ , it will remain at  $x$  for all

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### **Projected dynamical system - Wikipedia, the free -**

A projected dynamical system is given by the flow to the sign arises from a particular connection projected dynamical systems shares with variational

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### **Proceedings of the American Mathematical Society -**

Paul Dupuis and Anna Nagurney, Dynamical systems and inequalities and their applications, Projected Dynamical Systems and Variational

<http://www.ams.org/proc/2004-132-01/S0002-9939-03-07015-1/>

## **ON DIFFERENTIAL VARIATIONAL INEQUALITIES AND -**

discrete and continuous website: [www.aims.org](http://www.aims.org) dynamical systems supplement 2007 pp. 467 476 on differential variational inequalities and <http://aims.org/journals/pdfs.jsp?paperID=2854&mode=full>

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Projected dynamical systems and evolutionary variational inequalities via Hilbert spaces with applications (2004) <http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.131.1563>

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